

# MA3615 Groups and Symmetry

## Solutions to Exercise Sheet 6

- (a)  $C_3$  (same as rotational symmetries of a triangle).  
(b)  $D_8$  (same as all symmetries of a square).  
(c)  $D_4$  (same as all symmetries of a rectangle).  
(d)  $D_4$  (as (c)).  
(e)  $\{e\}$ .  
(f)  $C_4$  (same as rotational symmetries of a square).  
(g)  $D_6$  (same as all symmetries of a triangle).  
(h)  $D_2$ .

- First determine  $|G|$ . Look at the action of  $G$  on the set of white vertices. Each vertex can be mapped to any other by a rotation of the cube. So if  $v$  is any white vertex then  $|Orb_G(v)| = 4$ . The stabilizer of  $v$ ,  $G_v$ , consists of all rotations around the main diagonal through the vertex  $v$ , so  $|G_v| = 3$ . Hence using the orbit stabilizer theorem we get that

$$|G| = |Orb_G(v)| \cdot |G_v| = 4 \cdot 3 = 12.$$

We now construct an explicit isomorphism with  $A_4$ . Number the white vertices 1,2,3,4. The action of  $G$  on the set of white vertices gives a homomorphism

$$\psi : G \rightarrow S_4.$$

What is  $\text{Ker}\psi$ ? It's easy to see that if  $g \in G$  fixes all the white vertices then it must fix all the black vertices as well, so we must have  $g = e$ . Thus we have  $\text{Ker}\psi = \{e\}$ .

What is  $\text{Im}\psi$ ?  $G$  contains two types of rotations: rotations around a main diagonal of the cube and rotations around an axis through the middle of opposite faces. A rotation around a main diagonal corresponds, under  $\psi$ , to a permutation with cycle type of the form  $(a)(b, c, d)$ . A rotation around an axis through the middle of opposite faces corresponds, under  $\psi$ , to a permutation with cycle type  $(a, b)(c, d)$ . Both types of permutations lie in  $A_4$ . So we have in fact that

$$\psi : G \rightarrow A_4.$$

As  $\text{Ker}\psi = \{e\}$ , this map is one-to-one and as  $|G| = |A_4| = 12$ , it must be onto as well, so it is an isomorphism and we have  $G \cong A_4$  as required.

- Let  $G$  be the rotational symmetry group of this solid. Consider the action of  $G$  on the two tetrahedrons ( $|X| = 2$ ). It is easy to see that there is a rotation which sends one tetrahedron to the other. So if  $T$  is one of the tetrahedron, then  $|Orb_G(T)| = 2$ . What is the stabilizer of  $T$  in  $G$ ,  $G_T$ ? This is the rotational symmetry group of  $T$ , namely  $A_4$ . So we have  $|G_T| = |A_4| = 12$ . Thus using the Orbit-Stabilizer theorem we see that

$$|G| = |Orb_G(T)| \cdot |G_T| = 2 \cdot 12 = 24.$$

Using the classification of finite rotation groups we have that

$$G \cong C_{24}, D_{24} \quad \text{or} \quad S_4.$$

Now,  $G$  is not abelian, as  $G$  has a subgroup isomorphic to  $A_4$  (which is not abelian). So  $G$  cannot be isomorphic to  $C_{24}$ . Moreover,  $G$  does not contain a rotation of order 12. So  $G$  cannot be isomorphic to  $D_{24}$ , which has an element of order 12 (namely  $r$ ). Hence  $G \cong S_4$ .

4. Let  $G$  be the rotational symmetry group of the cuboctahedron. Consider the action of  $G$  on the set  $X$  consisting of all square faces ( $|X| = 6$ ). It is easy to see that there is always a rotation which sends a given square face to any other. So if  $F$  denotes a given square face then we have  $|Orb_G(F)| = 6$ . What is  $G_F$ ?  $G_F$  consists of the rotations around the axis passing through the middle of  $F$ . So  $|G_F| = 4$ . Thus using the orbit-stabilizer theorem we get that

$$|G| = |Orb_G(F)| \cdot |G_F| = 6 \cdot 4 = 24.$$

Using the classification we get  $G \cong C_{24}, D_{24}$  or  $S_4$ . As  $G$  is not abelian it cannot be isomorphic to  $C_{24}$  and as it does not contain a rotation of order 12, it cannot be isomorphic to  $D_{24}$ . Hence we must have  $G \cong S_4$  as required.