Parallel Combining: Benefits of Explicit Synchronization

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> > **OPODIS 2018**

Parallel Programs and Concurrent Data Structures

Parallel programs



Concurrent data structures



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Batched Data Structures

- Given a "batch" and a state produces a new state and a vector of responses.
- Parallel batched data structures
 - Static multithreading: PRAM, Bulk synchronous [Val90], asynchronous PRAM [Gib89],

- Dynamic multi-threading: spawn, sync, parallel-for, work-stealing
- Can we use the benefits of parallel batched data structures?

Combining [Oyama et al., 1999], [Hendler et al., 2010]

- Put request into publication list;
- Then, compete for a lock: if won becomes a combiner, otherwise, becomes a client;

- ► The combiner applies requests sequentially.
- ► Hierarchical Flat-Combining [Hendler et al., 2010]
 - Two levels of combining.

Parallel Combining

- Put request into publication list;
- Then, compete for a lock: if won becomes a combiner, otherwise, becomes a client;
- The combiner and clients apply requests in parallel using a parallel batched data structure.

Parallel Combining

```
execute(method, input):
request.method \leftarrow method
request.input \leftarrow input
req.status \leftarrow INITIAL
if \mathbb{C}.addRequest(req):
  A \leftarrow \mathbb{C}.getRequests()
  COMBINER CODE
  \mathbb{C}.release()
else:
  while req.status = INITIAL:
     nop
  CLIENT_CODE
return
```

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Read-Optimized Data Structures

Operations of two types:

- Read-only may proceed in parallel;
- Updates not always
- Combiner collects requests.
 - Read-only are performed in parallel on clients;
 - Updates are performed sequentially by the combiner.

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Read-Optimized Data Structures

The resulting concurrent data structures are linearizable.

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Read-Optimized Data Structures. Example

- Dynamic graph [Holm et al., 2001]:
 - Read-only: areConnected(u, v)
 - Update: addEdge(u, v), removeEdge(u, v)

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Dynamic graph. Experiments



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Priority queue

- Ordered set of values;
- Insert(v);
- ExtractMin().

Challenge: find a parallel batched algorithm with complexity that depends only on the batch size and the size of the heap.

Binary heap

- Binary heap stored in array a[1,..., s]: node i has children 2i and 2i + 1 with higher values.
- Algorithm [Gonnet and Munro, 1986]
 - ExtractMin(): swap a[1] and a[s], then sift-down;

Insert(v): traverse the path from the root to a[s + 1].

Parallel Batched Binary Heap. ExtractMin

Combiner with E extractMin requests:

- Locate E nodes with the smallest values using Dijkstra-like algorithm;
- Swap the values with E latest values a[s E + 1], ..., a[s];

- Initiate parallel sift-down on clients from the located nodes;
- Done using hand-over-hand locking.

Combiner with I insert requests:

- Target nodes: a[s + 1], ..., a[s + |I|];
- Locate |I| 1 split nodes;
- Sort $v_{s+1}, \ldots, v_{s+|I|}$ values to insert;
- Initiate a traversal from the root to target nodes, splitting set of values to insert into two sets in split nodes.



Parallel Batched Binary Heap

- The resulting concurrent binary heap is linearizable.
- Combiner and clients perform O(c + log s) RMRs in CC and DSM models each and O(c · (log c + log s)) RMRs in CC and DSM models in total.

Priority Queue. Experiments



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Conclusion

- It is possible to build efficient concurrent data structures from their parallel batched counterpart.
- We affirm it by considering two data structures: dynamic graph and priority queue.
- Which other data structures that can benefit from parallel combining?

For example, dynamic tree.

Thank you for your attention

 $\mathsf{Questions}?$



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